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# Ranking with Adaptive Neighbors

Muge Li, Liangyue Li, and Feiping Nie\*

**Abstract:** Retrieving the most similar objects in a large-scale database for a given query is a fundamental building block in many application domains, ranging from web searches, visual, cross media, to document retrievals. State-of-the-art approaches have mainly focused on capturing the underlying geometry of the data manifolds. Graph-based approaches, in particular, define various diffusion processes on weighted data graphs. Despite success, these approaches rely on fixed-weight graphs, making ranking sensitive to the input affinity matrix. In this study, we propose a new ranking algorithm that simultaneously learns the data affinity matrix and the ranking scores. The proposed optimization formulation assigns adaptive neighbors to each point in the data based on the local connectivity, and the smoothness constraint assigns similar ranking scores to similar data points. We develop a novel and efficient algorithm to solve the optimization problem. Evaluations using synthetic and real datasets suggest that the proposed algorithm can outperform the existing methods.

**Key words:** ranking; adaptive neighbors; manifold structure

## 1 Introduction

Retrieving the most similar objects in a large-scale database for a given query is a fundamental building block in many application domains, ranging from web search<sup>[1]</sup>, visual retrieval<sup>[2-6]</sup>, cross media retrieval<sup>[7]</sup>, to document retrieval<sup>[8]</sup>. The most straightforward approach to such retrieval tasks is to compute the pairwise similarities between objects in the Euclidean space as the ranking scores. Nonetheless, high-dimensional data often lie on a nonlinear manifold<sup>[9,10]</sup>.

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The Euclidean distance based approach largely ignores the intrinsic manifold structure and might degrade the retrieval performance.

State-of-the-art methods mainly focus on capturing the underlying geometry of the data manifold. The most common way is to first represent the data manifold using a weighted graph, wherein each vertex is a data object, and the edge weights are proportional to the pairwise similarities. All the vertices then repeatedly spread their affinities to their neighborhood via the weighted graph until a global stable state is reached. The various diffusion processes mainly differ in the transition matrix and the affinity update scheme<sup>[5]</sup>. Among others, the random walk transition matrix is widely used in PageRank<sup>[1]</sup>, random walk with restart<sup>[11]</sup>, self diffusion<sup>[12]</sup>, label propagation<sup>[13]</sup>, and graph transduction<sup>[14]</sup>. The random walk transition matrix is a row-stochastic matrix such that the transition probability is proportional to the edge weights. A slight variant is the symmetric normalized transition matrix used in the Ranking on Data Manifold method<sup>[15]</sup>. To reduce the effect of noisy nodes, random walks can be restricted to the  $k$  nearest neighbors by sparsifying the original weighted graph<sup>[16,17]</sup>. For iterative update of

the affinities, the random walk with restart allows for the random surfer to randomly jump to an arbitrary node. The modified diffusion process on the standard graph captures the high-order relations<sup>[17]</sup> and is equivalent to the diffusion process on the Kronecker product graph<sup>[18]</sup>. Despite success, graph-based ranking methods rely on fixed-weight graphs, making the ranking results sensitive to the input affinity matrix.

In this study, we propose the Ranking with Adaptive Neighbors (RAN) algorithm which simultaneously learns the data affinity matrix and the ranking scores. The proposed optimization explores two objectives. First, data points with smaller distance in the Euclidean space have high chance to be neighbors, i.e., more similar. In contrast to other graph-based ranking methods, the similarity is not computed a priori but is learned via optimizing the ranking scores. Consequently, the neighbors of each datum are adaptively assigned. Second, similar data points have similar ranking scores. This is essentially the smoothness constraint in graph transduction methods<sup>[19]</sup>. We develop a novel and efficient algorithm to solve the optimization problem. Evaluations using synthetic and real datasets suggest that the proposed ranking algorithm outperforms existing methods.

In Section 2, we present the proposed RAN algorithm. Next, in Section 3 we discuss the empirical evaluation results, and in Section 4, we summarize the conclusions.

**Notations:** Throughout the paper, the matrices are written as upper-case letters. For matrix  $M$ , the  $i$ -th row and  $(i, j)$ -th element of  $M$  are denoted by  $m_i$  and  $m_{ij}$ , respectively. An identity matrix is denoted by  $I$ , and  $\mathbf{1}$  denotes the column vector with all elements as 1. For vector  $v$  and matrix  $M$ ,  $v \geq 0$  and  $M \geq 0$  represent all the elements of  $v$  and  $M$  are nonnegative.

## 2 Ranking with Adaptive Neighbors

In this section, we discuss RAN algorithm and then the optimization approach for solving the objective function.

### 2.1 Proposed formulation

Given a set of data points  $\mathcal{X} = \{x_1, x_2, \dots, x_N\} \subseteq \mathbb{R}^d$  with a query indicator vector  $y = [y_1, y_2, \dots, y_N]^T \in \{0, 1\}^N$ , where  $y_1 = 1$  if  $x_i$  is the query and  $y_1 = 0$  otherwise, the task is to find a function  $f$  that assigns each point in the data  $x_i$  a ranking score  $f_i \in \mathbb{R}$  according to its relevance to the queries. We explore the

local connectivity of each point for ranking purposes and in particular consider the  $k$ -nearest points as the neighbors of a specific node.

Data points separated by small distances in the Euclidean space have high chance to be neighbors. We denote the probability that the  $i$ -th data point  $x_i$  and the  $j$ -th data point  $x_j$  are neighbors by  $s_{ij}$ . Intuitively, if the two data points are separated by a small distance, i.e.,  $\|x_i - x_j\|_2^2$  is small, then their probability  $s_{ij}$  of being connected is likely high. One way to find such probabilities  $s_{ij}|_{j=1}^N$  is to solve the following optimization problem:

$$\min_{s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1} \sum_{j=1}^N \|x_i - x_j\|_2^2 s_{ij} \quad (1)$$

where  $s_i \in \mathbb{R}^N$  is a vector with the  $j$ -th element as  $s_{ij}$ . Nonetheless, the above optimization problem has a trivial solution, that is,  $s_{ij} = 1$  for the nearest data point  $x_j$  of  $x_i$ , otherwise  $s_{ij} = 0$ . This can be addressed by adding a  $l_2$ -norm regularization on  $s_i$  to drag  $s_i$  closer to the center of mass of the simplex defined by  $s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1$ . This slight modification gives us the following optimization problem:

$$\min_{s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1} \sum_{j=1}^N (\|x_i - x_j\|_2^2 s_{ij} + \gamma s_{ij}^2) \quad (2)$$

where the second term is the regularization term and  $\gamma$  is the regularization parameter.

For each data point  $x_i$ , we compute its probability of connecting to other data points using Formula (2). As a result, we assign the neighbors of all the data points by solving the following problem:

$$\min_{\forall i, s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1} \sum_{i,j=1}^N (\|x_i - x_j\|_2^2 s_{ij} + \gamma s_{ij}^2) \quad (3)$$

Similar data points have similar ranking scores, essentially a smoothness constraint over the data graph. We assume the matrix  $S \in \mathbb{R}^{N \times N}$  is the similarity matrix obtained from assigning the neighbors, where each row is  $s_i^T$ . We write the smoothness constraint as

$$\sum_{i,j=1}^N (f_i - f_j)^2 s_{ij} = 2f^T L_S f \quad (4)$$

where  $f$  is the vector of ranking scores for all the data points,  $L_S = D_S - \frac{S^T + S}{2}$  is the Laplacian matrix of the affinity matrix, and the degree matrix  $D_S$  is a diagonal matrix with the  $i$ -th diagonal element defined as  $\sum_j (s_{ij} + s_{ji})/2$ .

Combining the above and using the information from

the query, we derive the final objective function:

$$\begin{aligned} \min_{S, f} \sum_{i, j=1}^n (\|x_i - x_j\|_2^2 s_{ij} + \gamma s_{ij}^2) + 2\lambda f^T L_S f + \\ (f - y)^T U (f - y) \\ \text{s.t. } \forall i, s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1 \end{aligned} \quad (5)$$

where  $U$  is a diagonal matrix with  $U_{ii} = \infty$  (a large constant) if  $x_i$  is the query, otherwise  $U_{ii} = 1$ . The last term is equivalent to  $\sum_{i=1}^n U_{ii} (f_i - y_i)^2$  to make the ranking results consistent with the queries. The queries are given much more weights as they reflect the user's search intentions. In non-queried examples, we do not know a priori whether they meet the user's intentions and give them lower weights. It is not easy to solve Formula (5) because  $L_S = D_S - \frac{S^T + S}{2}$  and  $D_S$  both depend on the similarity matrix  $S$ . In the next subsection, we propose a novel and efficient algorithm to solve this problem.

## 2.2 Optimization solutions

We propose to solve Formula (5) via an alternative optimization approach. We first fix  $S$  and then the problem transforms to

$$\min_f 2\lambda f^T L_S f + (f - y)^T U (f - y) \quad (6)$$

We take the derivative of the above objective function, w.r.t.  $f$ , and set it to 0, obtaining the following linear equation:

$$(2\lambda L_S + U)f = Uy \quad (7)$$

The solution is easily obtained as  $f = (2\lambda L_S + U)^{-1} Uy$ .

When  $f$  is fixed, Formula (5) transforms to

$$\min_S \sum_{i, j=1}^n (\|x_i - x_j\|_2^2 s_{ij} + \gamma s_{ij}^2) + 2\lambda f^T L_S f \quad (8)$$

$$\text{s.t. } \forall i, s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1 \quad (9)$$

And based on Eq. (4), it is written as

$$\begin{aligned} \min_S \sum_{i, j=1}^n (\|x_i - x_j\|_2^2 s_{ij} + \gamma s_{ij}^2 + \lambda (f_i - f_j)^2 s_{ij}), \\ \text{s.t. } \forall i, s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1 \end{aligned} \quad (10)$$

Because the summations are independent of each other given  $i$ , we can solve the following sub-problem individually for each  $i$ :

$$\begin{aligned} \min_{s_i} \sum_{j=1}^n (\|x_i - x_j\|_2^2 s_{ij} + \gamma s_{ij}^2 + \lambda (f_i - f_j)^2 s_{ij}), \\ \text{s.t. } s_i^T \mathbf{1} = 1, 0 \leq s_i \leq 1 \end{aligned} \quad (11)$$

We denote  $d_{ij}^x = \|x_i - x_j\|_2^2$  and  $d_{ij}^f = (f_i - f_j)^2$ , and denote  $d_i \in \mathbb{R}^N$  as a vector with the  $j$ -th element as  $d_{ij} = d_{ij}^x + \lambda d_{ij}^f$ . Then Formula (11) is reformulated as

$$\min_{s_i^T \mathbf{1}=1, 0 \leq s_i \leq 1} \|s_i + \frac{d_i}{2\gamma}\|_2^2 \quad (12)$$

Next, we will show how to solve this equation in a closed form using the Lagrange multipliers method. The Lagrangian function of the problem is

$$\mathcal{L}(s_i, \eta, \beta_i) = \frac{1}{2} \|s_i + \frac{d_i}{2\gamma}\|_2^2 - \eta (s_i^T \mathbf{1} - 1) - \beta_i^T s_i \quad (13)$$

where  $\eta$  and  $\beta_i$  are non-negative Lagrangian multipliers.

According to the KKT condition, the optimal solution is

$$s_{ij} = \left(-\frac{d_{ij}}{2\gamma_i} + \eta\right)_+ \quad (14)$$

where  $(x)_+$  is the shorthand for  $\max\{x, 0\}$ .

It is often desirable to focus on the locality of each point, as it can reduce the effect of noisy data and boost the performance in practice<sup>[20]</sup>. In this study, we will learn the sparse vector  $s_i$  and allow  $x_i$  to connect to its  $k$ -nearest neighbors. Such sparsification of  $S$  would minimize the computational cost.

We sort  $d_{ij}$  in ascending order such that  $d_{i1} \leq d_{i2} \leq \dots \leq d_{iN}$ . We want to learn the sparse  $s_i$  with only  $k$  nonzero elements, from Formula (14); thus we have  $s_{ik} > 0$  and  $s_{i, k+1} = 0$ . Therefore

$$\begin{cases} -\frac{d_{ik}}{2\gamma_i} + \eta > 0, \\ -\frac{d_{i, k+1}}{2\gamma_i} + \eta \leq 0 \end{cases} \quad (15)$$

Considering the constraint  $s_i^T \mathbf{1} = 1$ , we obtain

$$\sum_{j=1}^k \left(-\frac{d_{ij}}{2\gamma_i} + \eta\right) = 1 \Rightarrow \eta = \frac{1}{k} + \frac{1}{2k\gamma_i} \sum_{j=1}^k d_{ij} \quad (16)$$

Substituting Formula (16) into Formula (15), we obtain the following inequality for  $\gamma_i$ :

$$\frac{k}{2} d_{ik} - \frac{1}{2} \sum_{j=1}^k d_{ij} < \gamma_i \leq \frac{k}{2} d_{i, k+1} - \frac{1}{2} \sum_{j=1}^k d_{ij} \quad (17)$$

For the objective function in Formula (12) to have an optimal solution  $s_i$ , we set  $\gamma_i$  to

$$\gamma_i = \frac{k}{2} d_{i, k+1} - \frac{1}{2} \sum_{j=1}^k d_{ij} \quad (18)$$

The overall  $\gamma$  is set as the mean of all  $\gamma_i$ :

$$\gamma = \frac{1}{n} \sum_{i=1}^n \left(\frac{k}{2} d_{i, k+1} - \frac{1}{2} \sum_{j=1}^k d_{ij}\right) \quad (19)$$

The algorithm for solving the optimization problem in Formula (5) is summarized in Algorithm 1.

**Algorithm 1** Algorithm to solve problem in Eq. (5)

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**Input:** (1) Data matrix  $X \in \mathbb{R}^{n \times d}$ ,  
(2) Query indicator vector  $y$ ,  
(3) Parameters  $\gamma, \lambda$ .

**Output:** The ranking scores  $f$ .

- 1: Initialize  $S$  and compute  $L_S$  accordingly;
- 2: **while** not converged **do**
- 3: Define the diagonal matrix  $U$  as:  $U_{ii} = \infty$  if  $y_i = 1$  and  $U_{ii} = 1$  otherwise;
- 4: Update  $f$  by solving Eq. (7) as  $f = (2\lambda L_S + U)^{-1} U y$ ;
- 5: **for**  $i = 1, \dots, N$  **do**
- 6: Update  $i$ -th row of  $S$  by solving Formula (12)
- 7: **end for**
- 8: **end while**

---

### 3 Experiment

In this section, we show the performance of the proposed ranking algorithm RAN (Algorithm 1) on synthetic and real world datasets.

#### 3.1 Synthetic datasets

We randomly generate two synthetic datasets constructed as two-moon (Fig. 1) and three-ring (Fig. 2) patterns. A query is given in the upper moon and the innermost ring marked in red cross. The task is to rank the remaining data points according to their relevance to the query. We represent the ranking scores returned by RAN using the diameter of the data points such that larger points are more relevant. From Fig. 1, we observe that the ranking scores gradually decrease along the upper moon. The same decreasing trend is also observed in the lower moon. In addition, the ranking scores in the upper moon are generally much higher than in the lower moon. Such ranking outcome is intuitively expected. We make similar

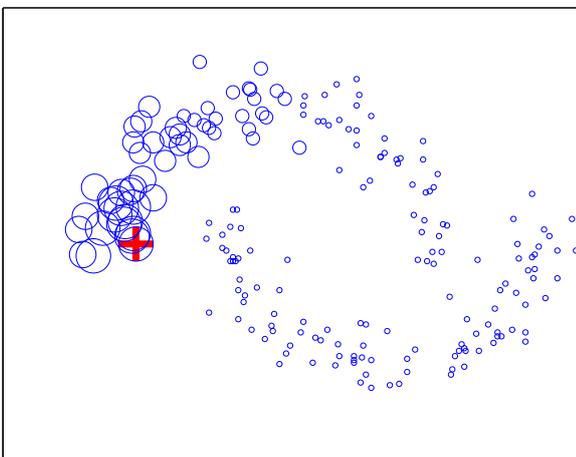


Fig. 1 Ranking example using two moons.

observations for three rings in Fig. 2. The data points in the innermost ring are more relevant than those in the middle ring, which are more relevant than those in the outermost ring. These results clearly show that the proposed RAN can capture the underlying manifold pretty well.

#### 3.2 Real dataset

We compare the retrieval performance on three real image datasets: Yale<sup>[21]</sup>, ORL<sup>[22]</sup>, and USPS<sup>[23]</sup>.

**Yale:** Yale contains face images of subjects at different poses and illumination conditions. We extract 11 images at different conditions for 15 subjects. Each image is down-sampled and normalized to zero mean and unit variance. The bandwidth for constructing the weighted graph for the graph based baselines is  $\sigma = 0.021$ . We set  $k = 5$  and  $\lambda = 90$  for RAN.

**ORL:** ORL contains 400 mages with ten different images for 40 different subjects each. The bandwidth for constructing the weighted graph for the graph based baselines is  $\sigma = 20$ . We set  $k = 5$  and  $\lambda = 0.1$  for RAN.

**USPS:** This dataset collects images of handwritten digits (0–9) from envelopes of the U.S. Postal Service. We extract 40 images for each digit and normalize them to  $16 \times 16$  pixels in gray scale. The bandwidth for constructing the weighted graph for the graph based baselines is  $\sigma = 0.8$ . We set  $k = 10$  and  $\lambda = 1.0$  for RAN.

On all the datasets, we use each image as query and measure the retrieval accuracy by ranking all the other images. We compare the proposed RAN algorithm with the Euclidean distance based baseline and several other diffusion methods, including Self-Diffusion

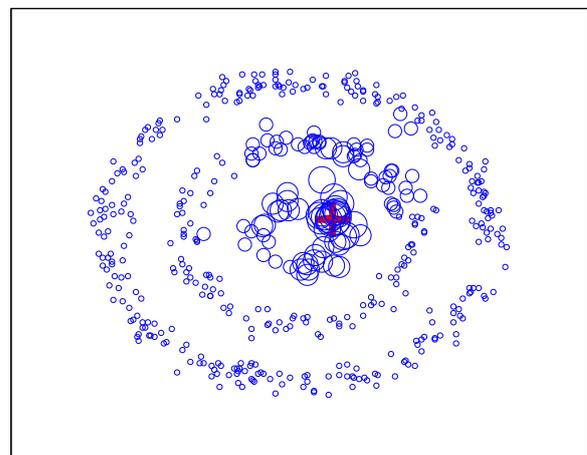
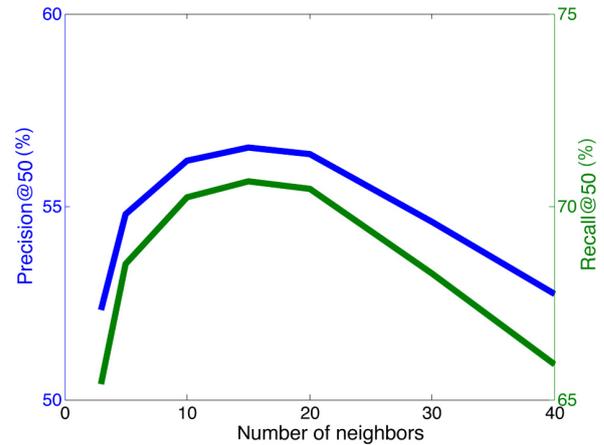


Fig. 2 Ranking example using three rings.

(SD)<sup>[12]</sup>, Personalized PageRank (PPR)<sup>[24]</sup>, Manifold Ranking<sup>[15]</sup>, and Graph Transduction (GT)<sup>[14]</sup>. The results are shown in Tables 1–3. From the results, we can see that the proposed RAN algorithm consistently outperforms all other methods. The straightforward Euclidean distance based baseline is the worst because it ignores the manifold structure in the data. The various diffusion based methods capture the manifold information to a certain extent, but they assume the weighted data graph is fixed. We instead adaptively learn the localized weighted graph optimized for the ranking. To study how the locality of the graph, i.e., the number of neighbors  $k$ , affects the retrieval performance, we show (Fig. 3) the retrieval performance by varying the number of neighbors on USPS dataset. As it can be seen, it is important to select a reasonable value for  $k$  for the retrieval. For USPS, the best performance can be achieved at  $k = 15$ .

## 4 Conclusion

We study the data ranking problem by capturing the underlying geometry of the data manifold. Instead of relying on the fixed-weight data graphs, we



**Fig. 3** Retrieval performance v.s. the number of neighbors on USPS.

propose a new ranking algorithm that is able to learn the data affinity matrix and the ranking scores simultaneously. The proposed optimization formulation assigns adaptive neighbors to each data point based on the local connectivity and the smoothness constraint assigns similar ranking scores to similar data points. An efficient algorithm is developed to solve the optimization problem. Evaluations using synthetic and real datasets demonstrate the superior performance of the proposed algorithm.

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**Table 1** Retrieval performance (%) for Yale.

Method	Precision@10	Recall@10
Euclidean distance	66.61	60.55
SD <sup>[12]</sup>	69.03	62.75
PPR <sup>[24]</sup>	69.03	62.75
Manifold Ranking <sup>[15]</sup>	68.85	62.59
GT <sup>[14]</sup>	68.91	62.65
RAN (ours)	<b>72.00</b>	<b>65.45</b>

**Table 2** Retrieval performance (%) for ORL.

Method	Precision@15	Recall@15
Euclidean distance	41.56	62.35
SD <sup>[12]</sup>	46.87	70.30
PPR <sup>[24]</sup>	47.15	70.73
Manifold ranking [15]	47.35	71.02
GT <sup>[14]</sup>	48.97	73.45
RAN (ours)	<b>49.02</b>	<b>73.53</b>

**Table 3** Retrieval performance (%) for USPS.

Method	Precision@50	Recall@50
Euclidean distance	45.53	56.91
SD <sup>[12]</sup>	47.42	59.27
PPR <sup>[24]</sup>	47.39	59.24
Manifold ranking <sup>[15]</sup>	47.42	59.28
GT <sup>[14]</sup>	46.18	57.72
RAN (ours)	<b>56.19</b>	<b>70.23</b>

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